

# Numerical Programming 2 (CSE) 2015

## Worksheet 5

### Exercise 1 (Sparse linear systems)

A TST matrix is a Toeplitz, symmetric, tridiagonal matrix<sup>1</sup>. Let  $M$  be the following  $d \times d$  TST matrix

$$M = \begin{pmatrix} \alpha & \beta & 0 & 0 & \dots \\ \beta & \alpha & \beta & 0 & \dots \\ 0 & \ddots & \ddots & \ddots & 0 \\ 0 & \dots & \beta & \alpha & \beta \\ 0 & \dots & 0 & \beta & \alpha \end{pmatrix} \quad (1)$$

verify that its eigenvalues and eigenvectors are respectively given by

$$\lambda_j = \alpha + 2\beta \cos\left(\frac{\pi j}{d+1}\right) \quad v_{j,l} = \sqrt{\frac{2}{d+1}} \sin\left(\frac{\pi j l}{d+1}\right) \quad \text{for } j, l = 1, \dots, d. \quad (2)$$

Consider the five-point stencil for discretizing the 2D Laplacian operator on a square, uniform grid. The structure of the resulting matrix defining the linear system, when using natural ordering, is given by

$$M = \frac{1}{h^2} \begin{pmatrix} S & T & O & \dots & O \\ T & S & T & \ddots & \vdots \\ O & \ddots & \ddots & \ddots & O \\ \vdots & \ddots & T & S & T \\ O & \dots & O & T & S \end{pmatrix}, \quad (3)$$

where  $O$  is the all zeros matrix and  $S$  and  $T$  are both TST matrices:

$$S = \begin{pmatrix} -4 & 1 & 0 & \dots & 0 \\ 1 & -4 & 1 & \ddots & \vdots \\ 0 & \ddots & \ddots & \ddots & 0 \\ \vdots & \ddots & 1 & -4 & 1 \\ 0 & \dots & 0 & 1 & -4 \end{pmatrix} \quad \text{and} \quad T = Id \quad (4)$$

The linear system to be solved then is given by

$$M \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix} \quad (5)$$

---

<sup>1</sup>A matrix is said to be Toeplitz if it is constant along its diagonals.

with  $x_l = [u_{1,l}, u_{2,l}, \dots, u_{n,l}]^T$  and  $b_l = [f_{1,l}, f_{2,l}, \dots, f_{n,l}]^T$ . Equivalently the system in (5) can be rewritten as

$$Tx_{l-1} + Sx_l + Tx_{l+1} = h^2 b_l \quad (6)$$

saying that the vectors-variables  $x_l$  are all coupled to each other.

Use the information given in (2) to rewrite (6) in an equivalent form in which the variables are decoupled, i.e. introduce new variables  $\tilde{x}_l$  such that, e.g.,  $\tilde{x}_{l,1}$  and  $\tilde{x}_{l,2}$  are uncoupled.

## Exercise 2 (Jacobi iteration)

Discretize the 1D Poisson equation

$$\Delta u(x) = f(x) \quad \text{on} \quad (0, 1)$$

with  $f(x) = \cos(\pi x)$  and Dirichlet boundary conditions  $u(0) = u(1) = 0$  by using three-point Finite Differences on an uniform grid with  $h = 1/N$ .

For  $N = 2^k$ ,  $k = 3, \dots, 8$ , solve the resulting system of linear equations using Jacobi iteration. Note that you will only get approximate solutions  $\tilde{u}_h \approx u_h$  of the discrete problem  $\Delta_h u_h = f$ . Determine experimentally how many iterations you need to obtain an approximation fulfilling

$$\|\Delta_h \tilde{u}_h - f\|_\infty \leq 10^{-3}$$

and plot the relationship between  $N$  and the required number of iterations.